

Research on the Application of Polynomial Direct Fitting to Platinum High-precision Temperature Measurement

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Although many methods can be used to conduct platinum resistor non-linear rectification, they cannot be put into wide use because of shortcomings such as narrow temperature range and complicated calculation of rectification. This article conducts fitting algorithm based on three temperature ranges of platinum resistor within temperature range and obtains cubic and quartic polynomial coefficients via the method of adjusting weight function using least square method after a brief summary of the regular method and problems existing in platinum resistor non-linear function inversion calculation. Meanwhile, fitting algorithm error distribution graph is also demonstrated. The maximum error is only $\pm 0.003^{\circ}\text{C}$ when applying quartic multinomial fitting algorithm within the range of 0-650 $^{\circ}\text{C}$. Finally, the advantages of multinomial direct fitting is further testified an analysis of C language calculation precision and data instances.

1. Introduction

Temperature is a physical quantity that represents objects' degree of hotness or coldness. It serves as an important parameter in industrial production and scientific experiments. Characterized by features such as stable performance, wide range of temperature measurement, easy calibration and good interchangeability, platinum resistor has been widely used in temperature measurement. Stipulated in International Temperature Scale ITS-90, specially structured platinum resistor is used as standard thermometer between -259 $^{\circ}\text{C}$ and 961.78 $^{\circ}\text{C}$.

Because non-linear relationship exists between platinum resistor's resistance value and temperature, non-linear operation (non-linear rectification) is required when temperature is reappeared. Based on scaling function and scaling table, non-linear operation is an indispensable part of high-accuracy temperature measurement with various methods. Although Newton Iteration Method can be used to solve platinum resistor scaling function and satisfactory results can be obtained after second iteration, iteration takes too long and internal memory is occupied too much. When Neural Network Approach is applied to conduct polynomial fitting for three times between 0 $^{\circ}\text{C}$ and 600 $^{\circ}\text{C}$ divided into six parts, the error is less than 0.02 $^{\circ}\text{C}$. The temperature is calculated on the basis of the resistor value via radical sign operation's analytic expression [Ping Yang]. The error $\leq 0.02^{\circ}\text{C}$ is obtained within the range of 0 $^{\circ}\text{C}$ -150 $^{\circ}\text{C}$ via symmetric function non-linear method and the error $\leq 0.05^{\circ}\text{C}$ is achieved within the range of 48 $^{\circ}\text{C}$ -50 $^{\circ}\text{C}$ via least square method.

Intelligent digital instrument whose core unit is an 8 bit single-byte-character single chip microcomputer is generally used to conduct high-accuracy temperature measurement. Therefore, the simple and direct algorithm used in studying the relationship between platinum resistor and temperature occupies little space and is valuable.

2. Non-linearity of Platinum Resistor (PT100)

Pt100 is the most frequently used temperature repetition element among Pt 10, Pt 100 and Pt 1000. The relationship between platinum resistor and temperature within the range of 0 $^{\circ}\text{C}$ -850 $^{\circ}\text{C}$ is:

$$R_t = R_0(1 + at + bt^2) \quad (1)$$

In the equation
a=3.90802E-3/ $^{\circ}\text{C}$

$b = -5.80195E-7/^{\circ}C$

$R(100^{\circ}C) / R(0^{\circ}C) = 1.38500$

Factor (1) indicates the relationship between the temperature and the resistor. Therefore, the temperature calculated via resistor value is an inversion process.

If resistor value R_F is set corresponding to upper limit of temperature range t_F and the temperature and resistor value within the measurement range is linear, the non-linear error is:

$$e_R = R_0(1 + at + bt^2) - \left[\frac{R_F - R_0}{t_F - t_0} \bullet t + R_0 \right] \tag{2}$$

Derivatives of formula (2) are calculated and ordered to be 0:

$$\frac{de_R}{dt} = aR_0 + 2bR_0t - \left[\frac{R_F - R_0}{t_F - t_0} \right] = 0$$

then:

$$t = [(R_F - R_0) / (t_F - t_0) - aR_0] / 2bR_0$$

The highest temperatures and resistor values of non-linear errors are $325^{\circ}C/6.127\Omega$ and $425^{\circ}C/10.478\Omega$ within the temperature ranges of $0-650^{\circ}C$ and $0-850^{\circ}C$, respectively. As is shown in graph 1, the reduced non-linear is about $27^{\circ}C$.

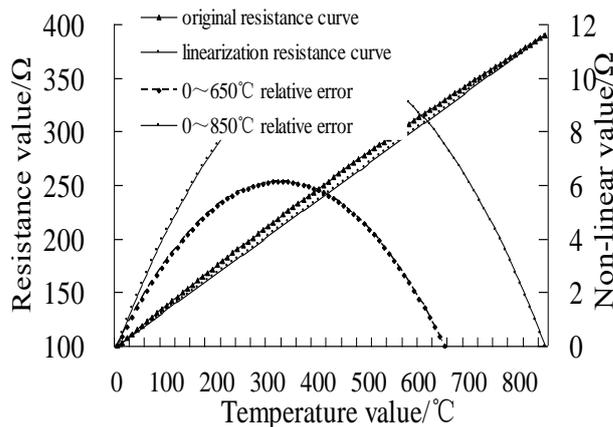


Figure 1: Non-linear errors distribution diagram within the range of $0-650^{\circ}C$ and $0-850^{\circ}C$

3. Least Square Method and Weight Function

Discrete points $(x_i, y_i) (i=0, 1, 2, \dots, m)$.

Approximate function curve $S(x)$ is constructed and the inherent law of the data is described, that is, selecting appropriate function class (collection)

$$\Phi = span\{\phi_0, \phi_1, \phi_2, \dots, \phi_n\}$$

$$= \{a_0\phi_0 + a_1\phi_1 + a_2\phi_2, \dots + a_n\phi_n | a_i \in R\}$$

$\phi_0, \phi_1, \phi_2, \dots, \phi_n$ is $n+1$ linearly independent continuous function on $[a, b]$. Find a function

$$S^*(x) = \sum_{i=0}^n a_i^* \phi_i(x) \quad (n < m)$$

making the deviation (residual error) of $S^*(x)$ and $y=f(x)$ on the above-mentioned $m+1$ points satisfy

$$\delta_i = \delta^*(x_i) - y_i \quad (i=0, 1, 2, \dots, m)$$

$$\begin{aligned} \|\delta\|_2^2 &= \sum_{i=0}^m \delta_i^2 = \sum_{i=0}^m \omega(x_i) [S^*(x_i) - y_i]^2 \\ &= \min_{s \in \Phi} \sum_{i=0}^m \omega(x_i) [S^*(x_i) - y_i]^2 \end{aligned} \quad (3)$$

among which

$$\delta = (\delta_1, \delta_2, \dots, \delta_m)^T$$

$$S(x) = \sum_{i=0}^n a_i \phi_j(x)$$

$\omega(x) \geq 0$ is the weight function between $[a, b]$. The function $S^*(x)$ of satisfiable formula (3) is least square solution.

Least square method aims at least square error (residual sum of squares). Linear models chosen according to shapes such as composite function, growth function, logarithmic function exponential function or logic function can be used when fitting curves. However, methods such as Taylor's series are still used for polynomial in program compilation, therefore, only polynomial is most suitable for sequential algorithm.

Although increasing the orders of polynomial can improve fitting effect in polynomial fitting, it may lead to ill-conditioned equations. If segment fitting is adopted, moving least square can be used to improve fitting precision.

Draw a t-R curve at certain temperature intervals for formula (1), and then conduct r-T fitting. Fitting based on temperature range is done in order to facilitate sequential algorithm. Considering approaching original function to the maximum or error distribution accompanies original function and showing symmetry, order constant whose weight function $\omega(x)$ is "1" to conduct fitting. Observe error distribution, adjust corresponding nodes' weight of weight function, and then fit again. Such process is repeated until error distribution approaches symmetry.

4. Platinum Resistor Polynomial Fitting

Polynomial can be loop calculation based on product-addition, which occupies small internal memory and has rapid calculation. See formula (4)

$$t_{(r)} = a_0 + (a_1 + (a_2 + (a_3 + a_4 \bullet r) \bullet r) \bullet r) \bullet r \quad (4)$$

$t_{(r)}$ is temperature value, r is actually measured platinum resistor value. Once platinum resistor value is measured, temperature value can be calculated via formula (3).

When using platinum resistor to measure temperature, 0-650°C is considered as standard temperature range, 650°C-850°C is extension range and 0-850°C is global range. Therefore, fitting calculations are conducted based on three ranges.

According to above principles, coefficients of polynomial (4) can be obtained via Matlab, see graph 1.

Concerning global range, maximum absolute value error of cubic polynomial is 0.1567°C, which satisfies on-site temperature control. Maximum absolute value error of quartic polynomial after fitting is 0.0249°C, which meets the precision requirement of 0.1°C.

When it comes to standard temperature range, maximum absolute value errors of cubic polynomial and quartic polynomial are 0.0320°C and 0.0024°C respectively. Quartic polynomial satisfies the precision requirement of 0.005°C.

Regarding extension range, maximum absolute value errors quadratic polynomial and cubic polynomial are 0.0194°C and 0.0053°C respectively.

As is shown in graph 1, cubic polynomials in these ranges can meet precision requirements of most engineering temperature measurements. Concerning measurement requirements, quartic polynomial can be applied. Extension range in graph 1 also shows that with regard to the same order, the smaller the range is, the higher the precision is when applying least square fit.

Table 1: Cubic polynomial and quartic polynomial graph within three temperature ranges

| range /°C | order | coefficients of each polynomial | | | | | +e _{max} | -e _{max} |
|-----------|-------|---------------------------------|----------------|----------------|----------------|----------------|-------------------|-------------------|
| | | a ₀ | a ₁ | a ₂ | a ₃ | a ₄ | | |
| 0-850 | 3 | -2.4942627E+02 | 2.4371743E+00 | 4.3341924E-04 | 1.3815819E-06 | | 0.1567 | -0.1452 |
| | 4 | -2.4668008E+02 | 2.3765713E+00 | 8.8576133E-04 | | 1.4772388E-09 | 0.0249 | -0.0242 |
| 0-650 | 3 | -2.4864735E+02 | 2.4216850E+00 | 5.2163889E-04 | 1.2304235E-06 | | 0.0320 | -0.0312 |
| | 4 | -2.46389305E+02 | 2.37230798E+00 | 9.01867745E-04 | | 1.42268923E-09 | 0.0024 | -0.0024 |
| 650-850 | 2 | -1.6886298E+02 | 1.8044518E+00 | 2.0658125E-03 | | | 0.0179 | -0.0194 |
| | 3 | -2.5720370E+02 | 2.5450480E+00 | | 1.9173044E-06 | | 0.0048 | -0.0053 |

In order to better show fitting effect, graph 2 and 3 indicate error distributions in global and standard ranges.

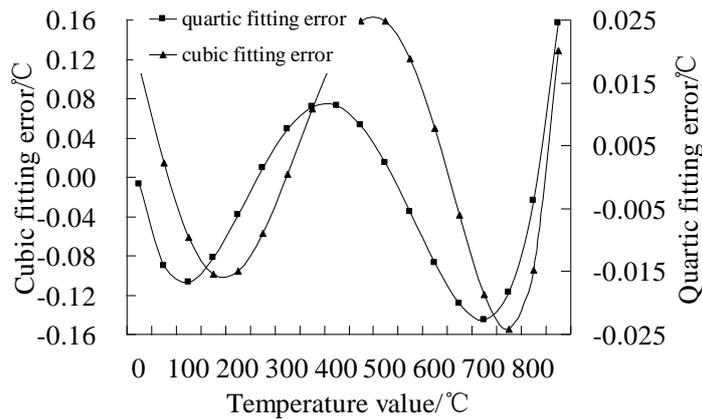


Figure 2: Error distribution of cubic and quartic fitting within the range of 0-850°C

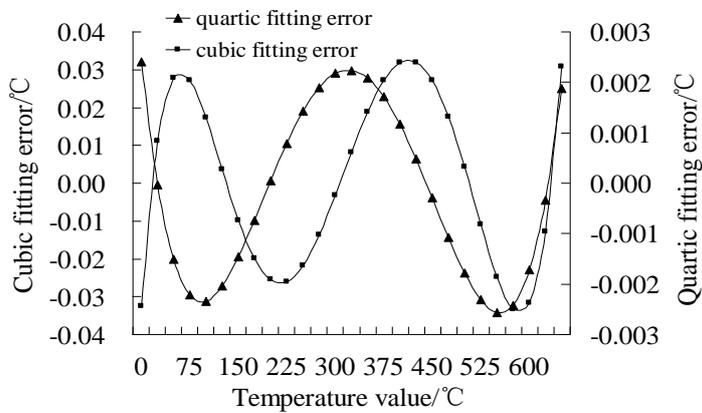


Figure 3: Error distribution of cubic and quartic fitting within the range of 0-650°C

5. C Language and Calculation Speed

C language is the widely used program in intelligent instrument using Single Chip Microcomputer and System On Chip. C language itself has no precision standard. Real variable is classified into three groups, namely, float, double, and long double, of which float takes up only 4 bits and has the highest calculation speed. In System On Chip, float is universally used in calculation considering its small internal memory.

Set standard 8051 Single Chip Microcomputer and 12MHz oscillation as an example, check with C language at Keil platform and conduct quartic polynomial fitting at 0-650°C. Formula (5) is obtained via calculating coefficients in graph 1 in formula (4). The calculation results and EXCEL calculation results are shown in graph 2.

$$\begin{aligned}
 t_{(r)} = & -246.38931 \\
 & +(2.3723080 \\
 & +(9.0186775E-04 \\
 & +(0+1.4226892E-09 \bullet r) \bullet r) \bullet r) \bullet r
 \end{aligned} \tag{5}$$

Table 2: C language and EXCEL calculation comparison

| Platinum resistance/ Ω | nominal temperature / $^{\circ}\text{C}$ | EXCEL calculation/ $^{\circ}\text{C}$ | C language calculation/ $^{\circ}\text{C}$ | |
|-------------------------------|--|---------------------------------------|--|---------|
| | | temperature | Temperature | error |
| 100.000 | 0.000 | 0.002439 | 0.002457 | -0.0025 |
| 119.395 | 50.000 | 49.99779 | 49.99779 | 0.0022 |
| 138.500 | 100.000 | 99.99869 | 99.99870 | 0.0013 |
| 157.315 | 150.000 | 150.0011 | 150.0011 | -0.0011 |
| 175.840 | 200.000 | 200.0029 | 200.0030 | -0.0030 |
| 194.074 | 250.000 | 250.0009 | 250.0009 | -0.0009 |
| 212.019 | 300.000 | 300.0007 | 300.0007 | -0.0007 |
| 229.673 | 350.000 | 349.9977 | 349.9977 | 0.0023 |
| 247.038 | 400.000 | 399.9985 | 399.9985 | 0.0015 |
| 264.112 | 450.000 | 449.9981 | 449.9980 | 0.0020 |
| 280.896 | 500.000 | 499.9993 | 499.9993 | 0.0007 |
| 297.390 | 550.000 | 550.0012 | 550.0013 | -0.0013 |
| 313.594 | 600.000 | 600.0018 | 600.0018 | -0.0018 |
| 329.508 | 650.000 | 649.9975 | 649.9976 | 0.0024 |

Program fitting calculation time is 1470MT (Machine Period), 1487MT and 1488MT with the resistor value being 100.000 Ω , 212.019 Ω and 329.508 Ω respectively, thus proving the high calculation speed of formula (4).

Table 2 also demonstrates the calculation correctness of Keli C.

6. Conclusions

Fitting algorithm based on three ranges within temperature range of platinum resistor is conducted and cubic and quartic polynomial coefficients are obtained via the method of adjusting weight function using least square method after a brief summary of the regular method and problems existing in platinum resistor non-linear function inversion calculation. Meanwhile, fitting algorithm error distribution graph is demonstrated. The maximum error is only $\pm 0.003^{\circ}\text{C}$ when applying quartic multinomial fitting algorithm within the range of 0-650°C. With the advantages of simple algorithm, small internal memory, and rapid arithmetic speed, multinomial fitting algorithm is especially suitable for single chip microcomputer or SOC using C language programming. The precision and speed of C language using single precision real type variable operations further testifies the advantages of multinomial fitting. The multinomial coefficients provided in this article can be directly applied to

platinum resistor temperature measurement. This method can also be applied to thermocouple temperature measurement.

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