

**Well-Posedness and Stability for a System of Klein-Gordon Equations****Naaïma Latioui<sup>1,\*</sup>, Amar Guesmia<sup>1</sup>, Amar Ouaoua<sup>2</sup>**<sup>1</sup>Laboratory of Applied Mathematics and History and Didactics of Mathematics "LAMAHIS",  
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Abstract. In this paper, we study the weak existence of solution for a non-linear hyperbolic coupled system of Klein-Gordon equations with memory and source terms using the Faedo-Galerkin method techniques and compactness results, we have demonstrated the uniqueness of the solution by using the classical technique. In addition, we show that the solution remains stable over time. The reaction of the proper Lyapunov function is the primary tool of the proof.

## 1. Introduction

In this paper, we consider a non-linear hyperbolic system of Klein-Gordon equations, defined as the following

$$\begin{cases} u_{tt} - \Delta u - \alpha u_t + k * \Delta u - \operatorname{div}(|v|^2 \nabla u) + u |\nabla v|^2 = 0 & \text{in } \Omega \times (0, T), \\ v_{tt} - \Delta v - \beta v_t + l * \Delta v - \operatorname{div}(|u|^2 \nabla v) + v |\nabla u|^2 = 0 & \text{in } \Omega \times (0, T), \end{cases} \quad (1.1)$$

with boundary conditions

$$u(x, t) = v(x, t) = 0 \quad \text{on } \Gamma \times (0, T), \quad (1.2)$$

$$u_t(x, t) = v_t(x, t) = 0 \quad \text{on } \Gamma \times (0, T), \quad (1.3)$$

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and Initial conditions

$$u(x, 0) = u_0(x), \quad v(x, 0) = v_0(x) \quad \text{on } \Omega, \quad (1.4)$$

$$u_t(x, 0) = u_1(x), \quad v_t(x, 0) = v_1(x) \quad \text{on } \Omega. \quad (1.5)$$

Where  $\Omega$  is a bounded domain of  $\mathbb{R}^n$  ( $n \geq 1$ ) with smooth boundary  $\Gamma$  and let  $T > 0$ ,  $\alpha$  and  $\beta$  are non-positive constants, and

$$(n * w)(t) = \int_0^t n(t-s)w(s)ds. \quad (1.6)$$

Several authors have studied the Klein-Gordon non-linear system among them

Medeiros & M. Miranda [8] considered the non-linear system

$$\begin{cases} \frac{\partial^2 u}{\partial t^2} - \Delta u + u - |v|^\rho |u|^\rho u = f_1, \\ \frac{\partial^2 v}{\partial t^2} - \Delta v + v - |u|^\rho |v|^\rho v = f_2, \end{cases} \quad (1.7)$$

they prove the existence and uniqueness of weak global solutions in  $\Omega \times [0, T]$ , where  $\rho$  is a real number meeting a specific condition and  $\Omega$  is any domain of  $\mathbb{R}^n$ .

D. Andrade & A. Mognon [2], considered the non-linear system with memory term

$$\begin{cases} u_{tt} - \Delta u + f(u, v) + k * \Delta u = 0, \\ v_{tt} - \Delta v + g(u, v) + l * \Delta v = 0, \end{cases} \quad (1.8)$$

for  $x \in \Omega$  and  $t > 0$  where

$$f(u, v) = |u|^{\rho-2} u |v|^\rho, \quad \text{and} \quad g(u, v) = |v|^{\rho-2} v |u|^\rho,$$

with

$$\rho > 0 \quad \text{if } n = 1, 2 \quad \text{and} \quad 1 < \rho \leq \frac{n-1}{n-2} \quad \text{if } n \geq 3,$$

they use the argument from Komornik and Zuazua [6] to prove the existence of weak and strong solutions in  $\Omega \times (0, T)$  given initial and boundary conditions.

A. T. Louredo & M. M. Miranda [7], considered the non-linear system

$$\begin{cases} u'' - \Delta u + \alpha v^2 u = 0, \\ v'' - \Delta v + \alpha u^2 v = 0, \end{cases} \quad (1.9)$$

with the nonlinear boundary conditions,

$$\begin{aligned} \frac{\partial u}{\partial \nu} + h_1(., u') &= 0 \quad \text{on } \Gamma_1 \times (0, \infty), \\ \frac{\partial v}{\partial \nu} + h_2(., v') &= 0 \quad \text{on } \Gamma_1 \times (0, \infty), \end{aligned}$$

and boundary conditions  $u = v = 0$  on  $(\Gamma/\Gamma_1) \times (0, \infty)$ , where  $\Omega$  is a bounded open set of  $\mathbb{R}^n$  ( $n \leq 3$ ),  $\alpha > 0$  a real number,  $\Gamma_1$  is a subset of the border  $\Gamma$  of  $\Omega$  and  $h_i$  a real function defined on  $\Gamma_1 \times (0, \infty)$ .

They use the Galerkin approach to demonstrate the existence of global solutions.

K. Zennir & A. Guesmia [10], considered the non-linear  $\kappa$ th-order with non-linear sources and memory terms

$$\begin{cases} u_1'' + (-1)^\kappa \Delta^\kappa u_1 + m_1^2 u_1 + \alpha_1(t) \int_0^t g_1(t-s) \Delta^\kappa u_1(x, s) ds + |u_1'|^{r-2} |u_1'| \\ = |u_1|^{p-2} u_1 |u_2|^p, \\ u_2'' + (-1)^\kappa \Delta^\kappa u_2 + m_2^2 u_2 + \alpha_2(t) \int_0^t g_2(t-s) \Delta^\kappa u_2(x, s) ds + |u_2'|^{r-2} |u_2'| \\ = |u_2|^{p-2} u_2 |u_1|^p, \end{cases} \quad (1.10)$$

using the potential well method, they verify the existence of global solutions in the a bounded domain  $\Omega$  of  $\mathbb{R}^n$ , where  $m_i = 1, 2$  are non-negative constants,  $r, p \geq 2, \kappa \geq 1$ .

C. L. Frota & A. Vicente [5], studied the non-linear system of Klien-Gordon with acoustic boundary conditions

$$\begin{cases} u'' - \Delta u + |v|^{\rho+2} |u^\rho| u = f_1 & \text{in } \Omega \times (0, T), \\ v'' - \Delta v + |u|^{\rho+2} |v^\rho| v = f_1 & \text{in } \Omega \times (0, T), \end{cases} \quad (1.11)$$

they demonstrate the existence of both global and weak solutions, as well as their uniqueness.

Our objective is to prove that the problem (1.1)-(1.5) has a weak and unique solution such that the kernel terms  $k, l$  have some hypothesis as well as using some ideas from articles ([2]) and ([9]).

## 2. Preliminaries

Let  $\Omega$  be a domain in  $\mathbb{R}^n$  with smooth boundary  $\Gamma$  let  $T > 0$ .

The inner product and norm in  $L^2(\Omega)$  are denoted by

$$\langle u, v \rangle = \int_{\Omega} u(x)v(x)dx, \quad |u|_2 = \left( \int_{\Omega} |u(x)|^2 dx \right)^{\frac{1}{2}}. \quad (2.1)$$

The norm in  $H_0^1(\Omega)$  is denoted by

$$\|u\|_{H_0^1(\Omega)} = \left( \int_{\Omega} |\nabla u|^2 dx \right)^{\frac{1}{2}}. \quad (2.2)$$

We assume that  $k, l: \mathbb{R}^+ \rightarrow \mathbb{R}^+$  are non-increasing differentiable functions satisfying :

$$h_1 = \left( 1 - \int_0^t l(s) ds \right) > 0 \quad \text{and} \quad k_1 = \left( 1 - \int_0^t k(s) ds \right) > 0, \quad (2.3)$$

and

$$k'(t) \leq -k(t), \quad l'(t) \leq -l(t). \quad (2.4)$$

If  $w = w(t, x)$  is a function in  $L^2(0, T; H_0^1(\Omega))$  and  $k$  is continuous we put:

$$(k \circ w)(t) = \int_0^t k(t-s) |\nabla w(t) - \nabla w(s)|_2^2 ds.$$

**Lemma 2.1.** [2]  $w \in C^1((0, T); H_0^1(\Omega))$ ,  $k \in C^1(0, \infty)$

$$\int_0^t k(t-s) \langle \nabla w(s) \nabla w'(t) \rangle ds = -\frac{1}{2} \frac{d}{dt} (k \circ w)(t) + \frac{1}{2} \frac{d}{dt} \left( \int_0^t k(s) ds \right) |\nabla w(t)|_2^2 + (k' \circ w)(t) - k(t) |\nabla w(t)|_2^2. \quad (2.5)$$

**Lemma 2.2.** [9] (**Young's Inequality**)

Let  $a, b \geq 0$  and  $\frac{1}{q} + \frac{1}{p} = 1$  for  $1 < p, q < +\infty$ , then one has the inequality  $ab \leq \delta a^q + c(\delta) b^p$ , where  $\delta > 0$  is an arbitrary constant, and  $c(\delta)$  is a positive constant depending on  $\delta$ .

**Lemma 2.3.** [1] (**Sobolev-Poincaré inequality**)

Let  $s$  be a number with  $2 \leq s < +\infty$  if  $n \leq 2$  and  $2 \leq s \leq \frac{2n}{n-2}$  if  $n > 2$ . Then there is a constant  $C$  depending on  $\Omega$  and  $s$  such that

$$\|u\|_s \leq C \|\nabla u\|_2, \quad u \in H_0^1.$$

**Theorem 2.1.** Let  $u_0, v_0 \in L^2(\Omega)$  and  $u_1, v_1 \in L^1(\Omega)$ . Then, under assumptions on two functions  $k$  and  $l$ , the problem (1.1)-(1.5) has a local solution  $(u(x, t), v(x, t))$  such that

$$u, v \in L^\infty(0, T; H_0^1(\Omega)) \cap L^\infty(0, T; L^2(\Omega)), \quad (2.6)$$

$$u_t, v_t \in L^\infty(0, T; L^2(\Omega)). \quad (2.7)$$

**Theorem 2.2.** Let  $u, v : \rightarrow L^2(\Omega)$  be functions in the class (2.6) and (2.7) satisfying from (1.1) to (1.5), with  $u, v \in H^2(\Omega)$ . Then the solution  $(u, v)$  obtained in Theorem (2.1) is unique.

### 3. Global Existence

**Step 1: Approximate solution.** Using the Faedo-Galerkin process, we will determine the existence of a local solution to the problem (1.1)-(1.5) in this section. Let  $\{w_i\}$  be a basis for both  $H^2(\Omega) \cap H_0^1(\Omega)$  and  $L^2(\Omega)$  for each positive integer  $m$  we put

$$V = \text{span}\{w_1, w_2, \dots, w_m\}.$$

we look for an approximate solution in the form

$$u_m(t) = \sum_{i=1}^m u_{im} w_i \quad \text{and} \quad v_m(t) = \sum_{i=1}^m v_{im} w_i,$$

satisfying the approximate problem

$$\int_{\Omega} \{u_{tt}^m - \Delta u^m - \alpha u_t^m\} w_i dx - \int_0^t k(t-s) \langle \nabla u^m(s), \nabla w_i \rangle ds \tag{3.1}$$

$$+ \int_{\Omega} |v^m|^2 \nabla u^m \nabla w_i dx + \int_{\Omega} u^m |\nabla v^m| w_i dx = 0,$$

$$\int_{\Omega} \{v_{tt}^m - \Delta v^m - \beta v_t^m\} w_i dx - \int_0^t l(t-s) \langle \nabla v^m(s), \nabla w_i \rangle ds \tag{3.2}$$

$$+ \int_{\Omega} v^m |\nabla u^m| w_i dx + \int_{\Omega} |u^m|^2 \nabla v^m \nabla w_i = 0,$$

with initial conditions satisfying

$$\begin{cases} u^m(0) = u_0^m, \sum_{i=1}^m a_{im} w_i = u_0^m \rightarrow u_0, & v^m(0) = v_0^m, \sum_{i=1}^m b_{im} w_i = v_0^m \rightarrow v_0 & \text{in } L^2(\Omega), \\ u_t^m(0) = u_1^m, \sum_{i=1}^m a_{im}^1 w_i = u_1^m \rightarrow u_1, & v_t^m(0) = v_1^m, \sum_{i=1}^m b_{im}^1 w_i = v_1^m \rightarrow v_1 & \text{in } L^1(\Omega). \end{cases} \tag{3.3}$$

Since the vectors  $\{w_i\}$  are linearly independent, this means  $\det(w_i, w_j) \neq 0$ , the latter ensuring that the problem admits a local solution  $(u^m(t), v^m(t))$  in the interval  $[0, T_m]$ .

**Step 2: A priori estimate.** Our system's energy functional  $E(t)$  is given by

$$2E(t) = |u_t^m|_{L^2(\Omega)}^2 + |v_t^m|_{L^2(\Omega)}^2 + (k \circ u^m)(t) + (l \circ v^m)(t) \tag{3.4}$$

$$+ \left(1 - \int_0^t k(s) ds\right) |\nabla u^m|_2^2 + \left(1 - \int_0^t l(s) ds\right) |\nabla v^m|_2^2 + |v^m \nabla u^m|_2^2 + |u^m \nabla v^m|_2^2.$$

After that, we multiply (3.1) by  $u_t$ , (3.2) by  $v_t$ , and use identity (2.5) to get

$$\frac{d}{dt} E(t) = (k' \circ u^m)(t) + (l' \circ v^m)(t) - k(t) |\nabla u^m|_2^2 - l(t) |\nabla v^m|_2^2 + \alpha |u_t^m|_2^2 + \beta |v_t^m|_2^2 \leq 0. \tag{3.5}$$

We found that  $\frac{d}{dt} E(t)$  is a non-positive function, this last indicates that  $E(t)$  is a non-increasing function, meaning there exists a positive constant  $C_1$ , independent of  $t$  and  $m$  such that

$$|u_t^m|_2^2 + |v_t^m|_2^2 + |\nabla u^m|_2^2 + |\nabla v^m|_2^2 + |u^m \nabla v^m|_2^2 + |v^m \nabla u^m|_2^2 \leq C_1. \tag{3.6}$$

From this estimation, deduce that  $T_m = T$ . In addition, we get

$$\begin{cases} u^m, v^m & \text{is bounded in } L^\infty(0, T; H_0^1(\Omega)), \\ u^m, v^m & \text{is bounded in } L^\infty(0, T; L^2(\Omega)), \\ u_t^m, v_t^m & \text{is bounded in } L^\infty(0, T; L^2(\Omega)). \end{cases} \tag{3.7}$$

By the Holder inequality, the embedding  $H_0^1(\Omega) \hookrightarrow L^6(\Omega)$  and (3.7), we obtain

$$|u^m \nabla v^m|_2^2 \leq \|u^m\|_{L^6(\Omega)}^2 \|\nabla v^m\|_{L^6(\Omega)}^4 \leq C_1, \tag{3.8}$$

$$\|v^m\|^2 \nabla u^m|_2^2 \leq \|v^m\|_{L^6(\Omega)}^4 \|\nabla u^m\|_{L^6(\Omega)}^2 \leq C_2 \quad \forall (u^m, v^m) \text{ in } H^2(\Omega). \tag{3.9}$$

Therefore

$$(u^m |\nabla v^m|^2) \text{ is bounded in } L^\infty(0, T; L^2(\Omega)), \quad (3.10)$$

$$(|v^m|^2 \nabla u^m) \text{ is bounded in } L^\infty(0, T; L^2(\Omega)). \quad (3.11)$$

Analogously

$$(v^m |\nabla u^m|^2) \text{ is bounded in } L^\infty(0, T; L^2(\Omega)), \quad (3.12)$$

$$(|u^m|^2 \nabla v^m) \text{ is bounded in } L^\infty(0, T; L^2(\Omega)). \quad (3.13)$$

**Step 3: passage to the limit.** From (3.7), (3.10), (3.11), (3.12) and (3.13) there exists a subsequence of  $(u^m)$  and a subsequence of  $(v^m)$ , denoted by same symbols, such that

$$\begin{cases} u^m \rightarrow u \text{ and } v^m \rightarrow v \text{ weak star in } L^\infty(0, T; H_0^1(\Omega)), \\ u^m \rightarrow u \text{ and } v^m \rightarrow v \text{ weak star in } L^\infty(0, T; L^2(\Omega)), \\ u_t^m \rightarrow u_t \text{ and } v_t^m \rightarrow v_t \text{ weak star in } L^\infty(0, T; L^2(\Omega)), \\ u^m |\nabla v^m|^2 \rightarrow \chi_1 \text{ weak star in } L^\infty(0, T; L^2(\Omega)), \\ v^m |\nabla u^m|^2 \rightarrow \chi_2 \text{ weak star in } L^\infty(0, T; L^2(\Omega)), \\ |v^m|^2 \nabla u^m \rightarrow \chi_3 \text{ weak star in } L^\infty(0, T; L^2(\Omega)), \\ |u^m|^2 \nabla v^m \rightarrow \chi_4 \text{ weak star in } L^\infty(0, T; L^2(\Omega)). \end{cases} \quad (3.14)$$

From (3.14) and Aubin-Lions compactness Lemma in ([3]), we obtain

$$u^m \rightarrow u, \quad v^m \rightarrow v \text{ strongly in } L^\infty(0, T; L^2(\Omega)), \quad (3.15)$$

since  $\nabla u^m$  and  $\nabla v^m$  are bounded, then we have

$$\begin{cases} u^m |\nabla v^m|^2 \rightarrow u |\nabla v|^2 \text{ strongly in } L^2(0, T; L^2(\Omega)), \\ v^m |\nabla u^m|^2 \rightarrow v |\nabla u|^2 \text{ strongly in } L^2(0, T; L^2(\Omega)), \\ |u^m|^2 \nabla v^m \rightarrow |u|^2 \nabla v \text{ strongly in } L^2(0, T; L^2(\Omega)), \\ |v^m|^2 \nabla u^m \rightarrow |v|^2 \nabla u \text{ strongly in } L^2(0, T; L^2(\Omega)). \end{cases} \quad (3.16)$$

Then, there exists a subsequences of  $u^m$  and  $v^m$ , which we will denote by  $u^m, v^m$  respectively, such that

$$\begin{cases} u^m |\nabla v^m|^2 \rightarrow u |\nabla v|^2 \text{ almost everywhere in } (0, T) \times \Omega, \\ v^m |\nabla u^m|^2 \rightarrow v |\nabla u|^2 \text{ almost everywhere in } (0, T) \times \Omega, \\ |u^m|^2 \nabla v^m \rightarrow |u|^2 \nabla v \text{ almost everywhere in } (0, T) \times \Omega, \\ |v^m|^2 \nabla u^m \rightarrow |v|^2 \nabla u \text{ almost everywhere in } (0, T) \times \Omega. \end{cases} \quad (3.17)$$

From Lemma (3.15) in ([11]) and (3.17) we deduce

$$\begin{cases} u^m |\nabla v^m|^2 \rightarrow u |\nabla v|^2 & \text{weakly in } L^\infty(0, T; L^2(\Omega)), \\ v^m |\nabla u^m|^2 \rightarrow v |\nabla u|^2 & \text{weakly in } L^\infty(0, T; L^2(\Omega)), \\ |u^m|^2 \nabla v^m \rightarrow |u|^2 \nabla v & \text{weakly in } L^\infty(0, T; L^2(\Omega)), \\ |v^m|^2 \nabla u^m \rightarrow |v|^2 \nabla u & \text{weakly in } L^\infty(0, T; L^2(\Omega)). \end{cases} \quad (3.18)$$

By the last formula (3.18) and (3.14) we get

$$\begin{aligned} \chi_1 &= u |\nabla v|^2, \\ \chi_2 &= v |\nabla u|^2, \\ \chi_3 &= |v|^2 \nabla u, \\ \chi_4 &= |u|^2 \nabla v. \end{aligned} \quad (3.19)$$

Taking  $w_i = 1$  in (3.1) become

$$\begin{aligned} (u_{tt}^m, 1) - \alpha (u_t^m, 1) + (u^m |\nabla v^m|^2, 1) &= 0 \\ |(u_{tt}^m, 1)| &= |\alpha (u_t^m, 1) - (u |\nabla v^m|^2, 1)|. \end{aligned} \quad (3.20)$$

Using the Cauchy Schwartz inequality, we have

$$\|u_{tt}^m\|_{L^1(\Omega)} \leq |\alpha| \|u_t^m\|_2 m^{\frac{1}{2}}(\Omega) + \|u^m |\nabla v^m|^2\|_2 m^{\frac{1}{2}}(\Omega),$$

such that,  $m(\Omega)$  is a measure of  $\Omega$ .

Since, the measure of  $\Omega$  is finite, and (3.14), we obtain

$$\|u_{tt}^m\|_{L^1(\Omega)} \leq C_1. \quad (3.21)$$

Analogously

$$\|v_{tt}^m\|_{L^1(\Omega)} \leq C_2. \quad (3.22)$$

Then

$$\begin{cases} u_{tt}^m & \text{is bounded in } L^\infty(0, T; L^1(\Omega)), \\ v_{tt}^m & \text{is bounded in } L^\infty(0, T; L^1(\Omega)). \end{cases} \quad (3.23)$$

Similarly we have

$$\begin{cases} u_{tt}^m \rightarrow u_{tt} & \text{weakly star in } L^\infty(0, T; L^1(\Omega)), \\ v_{tt}^m \rightarrow v_{tt} & \text{weakly star in } L^\infty(0, T; L^1(\Omega)). \end{cases} \quad (3.24)$$

From (3.14), (3.24) and lemma (3.1.7) in ([12]) with  $B = L^2(\Omega)$  and  $B = L^1(\Omega)$  we get

$$\begin{cases} u_0^m \rightarrow u(0), & v_0^m \rightarrow v(0) & \text{weakly star in } L^2(\Omega), \\ u_1^m \rightarrow u_1(0), & v_1^m \rightarrow v_1(0) & \text{weakly star in } L^1(\Omega). \end{cases} \quad (3.25)$$

From (3.25) and (3.3) we get

$$u(0) = u_0, \quad v(0) = v_0, \quad (3.26)$$

$$u_1(0) = u_1, \quad v_1(0) = v_1. \quad (3.27)$$

Setting up  $m \rightarrow \infty$  and passing to the limit in (3.1), (3.2), we obtained

$$\begin{aligned} & \int_{\Omega} \{u_{tt} - \Delta u - \alpha u_t\} w_i dx - \int_0^t k(t-s) \langle \nabla u(s), \nabla w_i \rangle ds \\ & + \int_{\Omega} |v|^2 \nabla u \nabla w_i dx + \int_{\Omega} u |\nabla v| w_i dx = 0, \end{aligned} \quad (3.28)$$

$$\begin{aligned} & \int_{\Omega} \{v_{tt} - \Delta v - \beta v_t\} w_i dx - \int_0^t l(t-s) \langle \nabla v(s), \nabla w_i \rangle ds \\ & + \int_{\Omega} v |\nabla u| w_i dx + \int_{\Omega} |u|^2 \nabla v \nabla w_i = 0. \end{aligned} \quad (3.29)$$

$i = 1, \dots, m$ . since  $(w_i)_{i=1}^{\infty}$  is a base of  $H_0^1(\Omega)$ , we deduce that  $(u, v)$  satisfies (1.1).

The proof is complete.

**Lemma 3.1.** *Let  $u_0, v_0 \in H_0^1(\Omega)$  and  $u_1, v_1 \in L^2(\Omega)$  be given. Assume that (2.3) and (2.4) are true. Then the problem's local solution (1.1)-(1.5) is global in time.*

**proof.** Since the map  $t \rightarrow E(t)$  is a non-increasing function, i.e there exists a positive constant  $C_1$ , independent of  $t$ , such that

Delete  $m$  from these equations

$$\begin{aligned} C_1 \geq 2E(t) &= |u_t|_{L^2(\Omega)}^2 + |v_t|_{L^2(\Omega)}^2 + (k \circ u)(t) + (l \circ v)(t) \\ &+ \left(1 - \int_0^t k(s) ds\right) |\nabla u|_2^2 + \left(1 - \int_0^t l(s) ds\right) |\nabla v|_2^2 + |v \nabla u|_2^2 + |u \nabla v|_2^2 > 0, \end{aligned} \quad (3.30)$$

which give

$$\begin{aligned} C_1 \geq 2E(t) &\geq |u_t|_{L^2(\Omega)}^2 + |v_t|_{L^2(\Omega)}^2 + \left(1 - \int_0^t k(s) ds\right) |\nabla u|_2^2 + \left(1 - \int_0^t l(s) ds\right) |\nabla v|_2^2 \\ &+ |v \nabla u|_2^2 + |u \nabla v|_2^2 > 0, \end{aligned} \quad (3.31)$$

consequently,  $\forall t \in [0, T]$ , we have  $|u_t|_{L^2(\Omega)}^2 + |v_t|_{L^2(\Omega)}^2 + |\nabla u|_2^2 + |\nabla v|_2^2 + |v \nabla u|_2^2 + |u \nabla v|_2^2 \leq C_1$ .

This deduces that the solution.



#### 4. Uniqueness

Let  $(u, v)$  and  $(u_1, v_1)$  two solutions of (1.1), we assume that  $U = u - u_1$  and  $V = v - v_1$  satisfy

$$U_{tt} - \Delta U - \alpha U_t + k * \Delta U - \operatorname{div}(|v|^2 \nabla u - |v_1|^2 \nabla u_1) + (u|\nabla v|^2 - u_1|\nabla v_1|^2) = 0 \quad \text{in } \Omega \times (0, T), \tag{4.1}$$

$$V_{tt} - \Delta V - \beta V_t + k * \Delta V - \operatorname{div}(|u|^2 \nabla v - |u_1|^2 \nabla v_1) + (v|\nabla u|^2 - v_1|\nabla u_1|^2) = 0 \quad \text{in } \Omega \times (0, T), \tag{4.2}$$

with

$$U(0) = V(0) = 0 \quad U_t(0) = V_t(0) = 0. \tag{4.3}$$

Let as put

$$2E_2(t) = |U_t|_2^2 + |V_t|_2^2 + (k \circ U)(t) + (l \circ V)(t) + \left(1 - \int_0^t k(s) ds\right) |\nabla U|_2^2 + \left(1 - \int_0^t l(s) ds\right) |\nabla V|_2^2. \tag{4.4}$$

Multiplying (4.1) by  $U_t(t)$  and (4.2) by  $(V_t(t))$  and summing up the product result we have

$$\begin{aligned} \frac{d}{dt} E_2(t) &\leq \int_{\Omega} \operatorname{div}(|v|^2 \nabla u - |v_1|^2 \nabla u_1) U_t - (u|\nabla v|^2 - u_1|\nabla v_1|^2) U_t dx \\ &\quad + \int_{\Omega} \operatorname{div}(|u|^2 \nabla v - |u_1|^2 \nabla v_1) V_t - (v|\nabla u|^2 - v_1|\nabla u_1|^2) V_t dx, \end{aligned} \tag{4.5}$$

$$\begin{aligned} \frac{d}{dt} E_2(t) &\leq \int_{\Omega} (|v|^2 \nabla u - |v_1|^2 \nabla u_1) |\nabla U_t| + (u|\nabla v|^2 - u_1|\nabla v_1|^2) |U_t| dx \\ &\quad + \int_{\Omega} (|u|^2 \nabla v - |u_1|^2 \nabla v_1) |\nabla V_t| + (v|\nabla u|^2 - v_1|\nabla u_1|^2) |V_t| dx, \end{aligned} \tag{4.6}$$

$$\begin{aligned} &\int_{\Omega} (|v|^2 \nabla u - |v_1|^2 \nabla u_1) \nabla U_t + (u|\nabla v|^2 - u_1|\nabla v_1|^2) U_t dx \\ &= \int_{\Omega} |v|^2 \nabla U \nabla U_t + \nabla u_1 [ |v|^2 - |v_1|^2 ] \nabla U_t + U_t |\nabla v|^2 U + u_1 [ |\nabla v|^2 - |\nabla v_1|^2 ] dx. \end{aligned} \tag{4.7}$$

From the mean value theorem, it follows that

$$\begin{aligned} &\int_{\Omega} (|v|^2 \nabla u - |v_1|^2 \nabla u_1) |\nabla U_t| + (u|\nabla v|^2 - u_1|\nabla v_1|^2) |U_t| dx \\ &\leq \int_{\Omega} |v|^2 |\nabla U| |\nabla U_t| + 2|\nabla u_1|^2 [ |v| + |v_1| ] |\nabla U_t| |V| + |\nabla v|^2 |U_t| |U|. \end{aligned}$$

Working in the same way as in argument of Lemma (2.2) in ([2]) there exists  $C > 0$  such that

$$\int_{\Omega} (|v|^2 \nabla u - |v_1|^2 \nabla u_1) |\nabla U_t| + (u|\nabla v|^2 - u_1|\nabla v_1|^2) |U_t| dx \leq C \{ |\nabla U|_2^2 + |\nabla V|_2^2 + |U_t|_2^2 \}.$$

Analogously we have

$$\int_{\Omega} (|u|^2 \nabla v - |u_1|^2 \nabla v_1) |\nabla V_t| + (v|\nabla u|^2 - v_1|\nabla u_1|^2) |V_t| dx \leq C \{ |\nabla V|_2^2 + |\nabla U|_2^2 + |V_t|_2^2 \},$$

and from (4.6) we have

$$\frac{d}{dt}E_2(t) \leq C \{|\nabla U|_2^2 + |\nabla V|_2^2 + |U_t|_2^2 + |V_t|_2^2\} \quad (4.8)$$

$$\frac{d}{dt}E_2(t) \leq CE_2(t). \quad (4.9)$$

Then, by using Gronwall's lemma (1.3) in ([4]) we get

$$|\nabla U|_2^2 = |\nabla V|_2^2 = |U_t|_2^2 = |V_t|_2^2 = 0. \quad (4.10)$$

This proves the uniqueness of the solution.

## 5. Stability

**Theorem 5.1.** *Let  $u_0, v_0 \in H_0^1(\Omega)$  and  $u_1, v_1 \in L^2(\Omega)$  be given. Assume that (2.3) and (2.4) hold. Then there exists two positive constants  $\mu_1$  and  $\mu_2$  independent of  $t$  such that  $0 < E(t) \leq \mu_1 e^{-\mu_2 t}, \forall t \geq 0$ .*

**Proof.** We define the function of Laypunov, for  $\epsilon > 0$  as follows

$$L(t) = E(t) + \epsilon \int_{\Omega} u_t u + v_t v dx. \quad (5.1)$$

We prove that  $L(t)$  and  $E(t)$  are equivalent, meaning that there exist two positive constants  $N$  and  $M$  depending on  $\epsilon$  such that for  $t \geq 0$

$$NE(t) \leq L(t) \leq ME(t). \quad (5.2)$$

From the Lemma (2.2), we have

$$L(t) \leq E(t) + \epsilon \left[ \frac{1}{2\delta} |u_t|_2^2 + \delta |u|_2^2 \right] + \epsilon \left[ \frac{1}{2\delta} |v_t|_2^2 + \delta |v|_2^2 \right].$$

By using the Poincaré inequality, we get

$$L(t) \leq E(t) + \epsilon \left[ \frac{1}{2\delta} |u_t|_2^2 + \delta C_1 |\nabla u|_2^2 \right] + \epsilon \left[ \frac{1}{2\delta} |v_t|_2^2 + \delta C_2 |\nabla v|_2^2 \right].$$

From (3.31) we have

$$L(t) \leq E(t) + \epsilon \left[ \frac{1}{\delta} E(t) + 2\delta \frac{C_1}{k_1} E(t) \right] + \epsilon \left[ \frac{1}{\delta} E(t) + 2\delta \frac{C_2}{l_1} E(t) \right]$$

$$L(t) \leq E(t) + 2\epsilon \frac{1}{\delta} E(t) + 2\epsilon \delta \frac{C_1}{k_1} E(t) + 2\epsilon \delta \frac{C_2}{l_1} E(t)$$

$$L(t) \leq ME(t) \quad \text{such that} \quad M = 1 + 2\epsilon \frac{1}{\delta} + 2\epsilon \delta \frac{C_1}{k_1} + 2\epsilon \delta \frac{C_2}{l_1}.$$

On the other hand, we have

$$\begin{aligned} L(t) &\geq E(t) - \epsilon \left[ \frac{1}{2\delta} |u_t|_2^2 + \delta |u|_2^2 \right] - \epsilon \left[ \frac{1}{2\delta} |v_t|_2^2 + \delta |v|_2^2 \right] \\ &\geq E(t) - \epsilon \left[ \frac{1}{2\delta} |u_t|_2^2 + \delta C_1 |\nabla u|_2^2 \right] - \epsilon \left[ \frac{1}{2\delta} |v_t|_2^2 + \delta C_2 |\nabla v|_2^2 \right] \\ &\geq E(t) - \epsilon \left[ \frac{1}{\delta} E(t) + 2\delta \frac{C_1}{k_1} E(t) \right] - \epsilon \left[ \frac{1}{\delta} E(t) + 2\delta \frac{C_2}{h_1} E(t) \right], \end{aligned}$$

$$L(t) \geq NE(t) \quad \text{such that} \quad N = 1 - 2\epsilon \frac{1}{\delta} - 2\epsilon \delta \frac{C_1}{k_1} - 2\epsilon \delta \frac{C_2}{h_1}.$$

Now we have

$$\frac{d}{dt}L(t) = \frac{d}{dt}E(t) + \epsilon \int_{\Omega} [u_t^2 + u_{tt}u + v_t^2 + v_{tt}v] dx \tag{5.3}$$

$$\begin{aligned} \epsilon \int_{\Omega} u_{tt}u dx &= \epsilon \int_{\Omega} [u \cdot \Delta u + \alpha u u_t - u \cdot k * \Delta u + u \cdot \text{div}(|v|^2 \nabla u) - u |\nabla v|^2 \cdot u] dx \\ &\leq \epsilon \left[ -|\nabla u|_2^2 + \alpha \frac{1}{2\delta} |u_t|_2^2 + \alpha \delta |u|_2^2 - |v \nabla u|_2^2 - |u \nabla v|_2^2 + \int_{\Omega} \nabla u \int_0^t k(t-s) \nabla u(s) ds dx \right] \\ &\leq \epsilon \left[ -|\nabla u|_2^2 + \alpha \frac{1}{2\delta} |u_t|_2^2 + \alpha C_1 \delta |\nabla u|_2^2 - |v \nabla u|_2^2 - |u \nabla v|_2^2 + \int_{\Omega} \nabla u \int_0^t k(t-s) \nabla u(s) ds dx \right]. \end{aligned} \tag{5.4}$$

Analogous

$$\begin{aligned} \epsilon \int_{\Omega} v_{tt}v dx &= \epsilon \int_{\Omega} [v \cdot \Delta v + \beta v v_t - v \cdot k * \Delta v + v \cdot \text{div}(|u|^2 \nabla v) - v |\nabla u|^2 \cdot v] dx \\ &\leq \epsilon \left[ -|\nabla v|_2^2 + \beta \frac{1}{2\delta} |v_t|_2^2 + \beta C_1 \delta |\nabla v|_2^2 - |u \nabla v|_2^2 - |v \nabla u|_2^2 + \int_{\Omega} \nabla v \int_0^t l(t-s) \nabla v(s) ds dx \right]. \end{aligned} \tag{5.5}$$

$$\begin{aligned} \frac{d}{dt}L(t) &\leq \frac{d}{dt}E(t) + \epsilon |u_t|_2^2 + \epsilon |v_t|_2^2 \\ &\quad - \epsilon |\nabla u|_2^2 + \epsilon \alpha \frac{1}{2\delta} |u_t|_2^2 + \epsilon \alpha C_1 \delta |\nabla u|_2^2 - \epsilon |v \nabla u|_2^2 - \epsilon |u \nabla v|_2^2 + \epsilon \int_{\Omega} \nabla u \int_0^t k(t-s) \nabla u(s) ds dx \\ &\quad - \epsilon |\nabla v|_2^2 + \epsilon \beta \frac{1}{2\delta} |v_t|_2^2 + \epsilon \beta C_1 \delta |\nabla v|_2^2 - \epsilon |u \nabla v|_2^2 - \epsilon |v \nabla u|_2^2 + \epsilon \int_{\Omega} \nabla v \int_0^t l(t-s) \nabla v(s) ds dx. \end{aligned} \tag{5.6}$$

The last term of relation (5.6) can be estimated as follow.

$$\begin{aligned} &\left| \int_{\Omega} \nabla u \int_0^t k(t-s) \nabla u(s) ds dx \right| \\ &\leq \int_{\Omega} \left( \int_0^t k(t-s) |\nabla u(s) - \nabla u(t)| ds \right) dx + \int_0^t k(s) ds |\nabla u|_2^2 \\ &\leq (1 + \eta)(1 - k_1) |\nabla u|_2^2 + \frac{1}{4\eta} (k \circ \nabla u)(t) \quad \text{for } \eta > 0. \end{aligned} \tag{5.7}$$

Analogously

$$\begin{aligned} & \left| \int_{\Omega} \nabla v \int_0^t l(t-s) \nabla v(s) ds dx \right| \\ & \leq (1+\eta)(1-l_1) |\nabla v|_2^2 + \frac{1}{4\eta} (l \circ \nabla v)(t) \quad \text{for } \eta > 0. \end{aligned}$$

So

$$\begin{aligned} \frac{d}{dt} L(t) & \leq (k' \circ u)(t) + (l' \circ v)(t) - k(t) |\nabla u|_2^2 - l(t) |\nabla v|_2^2 + \alpha |u_t|_2^2 + \beta |v_t|_2^2 + \epsilon |u_t|_2^2 + \epsilon |v_t|_2^2 \\ & - \epsilon |\nabla u|_2^2 + \epsilon \alpha \frac{1}{2\delta} |u_t|_2^2 + \epsilon \alpha C_1 \delta |\nabla u|_2^2 - \epsilon |v \nabla u|_2^2 - \epsilon |u \nabla v|_2^2 + \epsilon (1+\eta)(1-k_1) |\nabla u|_2^2 \\ & + \epsilon \frac{1}{4\eta} (k \circ \nabla u)(t) - \epsilon |\nabla v|_2^2 + \epsilon \beta \frac{1}{2\delta} |v_t|_2^2 + \epsilon \beta C_1 \delta |\nabla v|_2^2 - \epsilon |u \nabla v|_2^2 - \epsilon |v \nabla u|_2^2 \\ & + \epsilon (1+\eta)(1-l_1) |\nabla v|_2^2 + \epsilon \frac{1}{4\eta} (l \circ \nabla v)(t), \end{aligned} \quad (5.8)$$

so

$$\begin{aligned} \frac{d}{dt} L(t) & \leq \left( \alpha + \epsilon + \epsilon \alpha \frac{1}{2\delta} \right) |u_t|_2^2 + \left( \beta + \epsilon + \epsilon \beta \frac{1}{2\delta} \right) |v_t|_2^2 \\ & + (-k(t) - \epsilon + \epsilon \alpha C_1 \delta + \epsilon (1+\eta)(1-k_1)) |\nabla u|_2^2 \\ & + (-l(t) - \epsilon + \epsilon \beta C_1 \delta + \epsilon (1+\eta)(1-l_1)) |\nabla v|_2^2 + (-2\epsilon - 1) |v \nabla u|_2^2 + (-2\epsilon - 1) |u \nabla v|_2^2 \\ & - (k \circ u)(t) - (l \circ v)(t) + |u \nabla v|_2^2 + |v \nabla u|_2^2 + \epsilon \frac{1}{4\eta} (k \circ \nabla u)(t) + \epsilon \frac{1}{4\eta} (l \circ \nabla v)(t), \end{aligned} \quad (5.9)$$

so

$$\frac{d}{dt} L(t) \leq \gamma E(t) + \lambda, \quad (5.10)$$

We choosing  $\epsilon$  small enough, such that

$$\begin{aligned} \gamma = \text{Min} & \left( \alpha + \epsilon + \epsilon \alpha \frac{1}{2\delta}; \beta + \epsilon + \epsilon \beta \frac{1}{2\delta}; -k(t) - \epsilon + \epsilon \alpha C_1 \delta + \epsilon (1+\eta)(1-k_1) \right. \\ & \left. - l(t) - \epsilon + \epsilon \beta C_1 \delta + \epsilon (1+\eta)(1-l_1); (-2\epsilon - 1); -1 \right) < 0, \end{aligned} \quad (5.11)$$

and

$$\lambda = |u \nabla v|_2^2 + |v \nabla u|_2^2 + \epsilon \frac{1}{4\eta} (k \circ \nabla u)(t) + \epsilon \frac{1}{4\eta} (l \circ \nabla v)(t). \quad (5.12)$$

From (5.2), we have

$$\frac{d}{dt} L(t) \leq \frac{\gamma}{M} L(t) + \lambda, \quad (5.13)$$

by integrating the previous differential inequality (5.13) between 0 and t, we obtain the following estimate for the function L

$$L(t) \leq c e^{\frac{\gamma}{M} t} - \frac{\lambda M}{\gamma}, \quad \forall t \geq 0, \quad (5.14)$$

by using (5.2), we conclude

$$E(t) \leq c_1 e^{\frac{\gamma}{M} t} - \frac{\lambda M}{\gamma N}, \quad \forall t \geq 0. \quad (5.15)$$

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